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A systematic construction of representations of quaternionic type

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Alterman Conference Brasov - August 4th, 2016

### 1 Polyhedral groups, Platonic solids and root systems

- 2 A Clifford way of doing orthogonal transformations
- 3 Clifford algebra and quaternions
- 4 Representations from multivector groups: representations of quaternionic type





# **Platonic Solids**



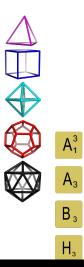
Platonic Solid	Group	root system	
Tetrahedron	A <sub>3</sub>	Cuboctahedron	
	$A_1^{\tilde{3}}$	Octahedron	
Octahedron	<i>B</i> <sub>3</sub>	Cuboctahedron	
Cube		+ Octahedron	
Icosahedron	H <sub>3</sub>	Icosidodecahedron	
Dodecahedron			

#### Platonic Solids have been known for millennia

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# **Platonic Solids**



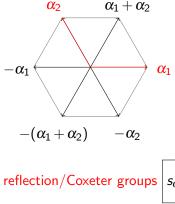
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- Platonic Solids have been known for millennia
- Described by Coxeter groups

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2

#### Root systems



Root system  $\Phi$ : set of vectors  $\alpha$  in a vector space with an inner product such that

$$1. \Phi \cap \mathbb{R}\alpha = \{-\alpha, \alpha\} \forall \alpha \in \Phi$$

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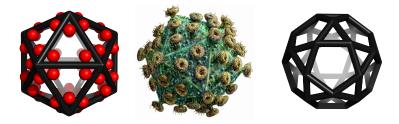
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2. 
$$s_{\alpha} \Phi = \Phi \ \forall \ \alpha \in \Phi$$

Simple roots: express every element of  $\Phi$  via a <u>Z-linear combination</u>.

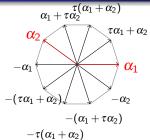
$$\mathsf{ps}\left|s_{\alpha}: v \to s_{\alpha}(v) = v - 2\frac{(v|\alpha)}{(\alpha|\alpha)}\alpha\right|$$

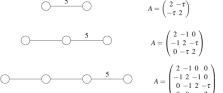
# The Icosahedron



- Rotational icosahedral group is  $I = A_5$  of order 60
- Full icosahedral group is H<sub>3</sub> of order 120 (including reflections/inversion); generated by the root system icosidodecahedron

## Non-crystallographic Coxeter groups $H_2 \subset H_3 \subset H_4$ .





 $H_2 \subset H_3 \subset H_4$ : 10, 120, 14,400 elements, the only Coxeter groups that generate rotational symmetries of order 5 linear combinations now in the extended integer ring

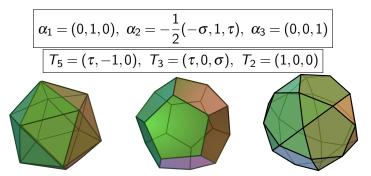
$$\boxed{\mathbb{Z}[\tau] = \{a + \tau b | a, b \in \mathbb{Z}\}} \text{ golden ratio} \qquad \tau = \frac{1}{2}(1 + \sqrt{5}) = 2\cos\frac{\pi}{5}$$
$$\boxed{x^2 = x + 1} \qquad \tau' = \sigma = \frac{1}{2}(1 - \sqrt{5}) = 2\cos\frac{2\pi}{5} \qquad \tau + \sigma = 1, \tau \sigma = -1$$

# Cartan-Dynkin diagrams

Coxeter-Dynkin diagrams: node = simple root, no link = roots orthogonal i.e. angle  $\frac{\pi}{2}$ , simple link = roots at angle  $\frac{\pi}{3}$ , link with label m = angle  $\frac{\pi}{m}$ .  $A_2 \circ \cdots \circ H_2 \circ \frac{5}{\circ} \circ I_2(n) \circ \frac{n}{\circ}$  $A_3 \circ \cdots \circ B_3 \circ \frac{4}{\circ} \circ H_3 \circ \frac{5}{\circ}$  $D_4 \circ \frac{6}{\circ} \circ F_4 \circ \frac{4}{\circ} \circ H_4 \circ \frac{5}{\circ} \circ \frac{6}{\circ}$  $E_8 \circ \cdots \circ \frac{6}{\circ} \circ \frac{6}{\circ} \circ \frac{6}{\circ}$ 

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 $H_3$  – the icosahedral group -5



Icosahedron, Dodecahedron, Icosidodecahedron ( $H_3$  root system)

#### Polyhedral groups, Platonic solids and root systems

### 2 A Clifford way of doing orthogonal transformations

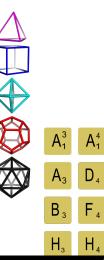
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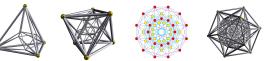




# **Platonic Solids**



- Concatenating reflections gives Clifford spinors (binary polyhedral groups)
- These induce 4D root systems
  - $R = a_0 + a_1 e_2 e_3 + a_2 e_3 e_1 + a_3 e_1 e_2 \Rightarrow$  $R\tilde{R} = a_0^2 + a_1^2 + a_2^2 + a_3^2$
- 4D analogues of the Platonic Solids and give rise to 4D Coxeter groups



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A systematic construction of representations of quaternionic ty

# Clifford Algebra and orthogonal transformations

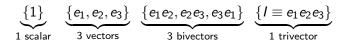
- Geometric Product for two vectors  $ab \equiv a \cdot b + a \wedge b$
- Inner product is symmetric part  $a \cdot b = \frac{1}{2}(ab+ba)$
- Reflecting *a* in *n* is given by  $a' = a 2(a \cdot n)n = -nan$  (*n* and -n doubly cover the same reflection)
- Via Cartan-Dieudonné theorem any orthogonal transformation can be written as successive reflections, which are doubly covered by Clifford versors/pinors *A*

$$\overline{x' = \pm n_1 n_2 \dots n_k x n_k \dots n_2 n_1} =: \pm A x \tilde{A}$$

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# Clifford Algebra of 3D

• E.g. Pauli algebra in 3D (likewise for Dirac algebra in 4D) is



- We can multiply together root vectors in this algebra  $\alpha_i \alpha_j \dots$
- A general element has 8 components, even products (rotations/spinors) have four components:

$$R = a_0 + a_1 e_2 e_3 + a_2 e_3 e_1 + a_3 e_1 e_2 \Rightarrow R\tilde{R} = a_0^2 + a_1^2 + a_2^2 + a_3^2$$

• So behaves as a 4D Euclidean object - inner product

$$(R_1, R_2) = \frac{1}{2}(R_2\tilde{R_1} + R_1\tilde{R_2})$$

# Spinors from reflections



- The 6 roots (±1,0,0) and permutations in  $A_1 \times A_1 \times A_1$  generate 8 spinors:
- $\pm e_1, \pm e_2, \pm e_3$  give the 8 spinors  $\pm 1, \pm e_1e_2, \pm e_2e_3, \pm e_3e_1$
- This is a discrete spinor group isomorphic to the quaternion group *Q*.
- As 4D vectors these are  $(\pm 1, 0, 0, 0)$  and permutations, the 8 roots of  $A_1 \times A_1 \times A_1 \times A_1$  (the 16-cell).

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#### Induction Theorem – root systems

 Induction Theorem: Every rank-3 root system induces a rank-4 root system (and thereby Coxeter groups) via these 3D spinor groups.

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- Induction Theorem: Every rank-3 root system induces a rank-4 root system (and thereby Coxeter groups) via these 3D spinor groups.
- Check axioms:

1. 
$$\Phi \cap \mathbb{R}\alpha = \{-\alpha, \alpha\} \ \forall \ \alpha \in \Phi$$

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$$s_{\alpha} \Phi = \Phi \ \forall \ \alpha \in \Phi$$

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### Induction Theorem – root systems

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• Proof: 1. R and -R are in a spinor group by construction (double cover of orthogonal transformations), 2. closure under reflections is guaranteed by the closure property of the spinor group (with a twist:  $-R_1\tilde{R}_2R_1$ )

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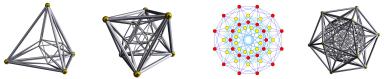
# Spinors from reflections

- Symmetry groups of the Platonic Solids:
- The 6/12/18/30 reflections in  $A_1 \times A_1 \times A_1/A_3/B_3/H_3$ generate 8/24/48/120 spinors.
- The discrete spinor group is isomorphic to the quaternion group Q / binary tetrahedral group 2T / binary octahedral group 2O / binary icosahedral group 2I).

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# Spinors and Polytopes

- Can reinterpret spinors in  $\mathbb{R}^3$  as vectors in  $\mathbb{R}^4$
- Give (exceptional) root systems  $(D_4, F_4, H_4)$
- They constitute the vertices of the 16-cell, 24-cell, 24-cell and dual 24-cell and the 600-cell
- These are 4D analogues of the Platonic Solids. Strange symmetries better understood in terms of 3D spinors



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# Root systems in three and four dimensions

The spinors from the reflections in the rank-3 Coxeter group via the geometric product are the binary polyhedral groups Q, 2T, 2O and 2I, which generate (mostly exceptional) rank-4 groups, but not known why, and why the 'mysterious symmetries'.

rank-3 group	diagram	binary	rank-4 group	diagram
$A_1 \times A_1 \times A_1$	000	Q	$A_1 \times A_1 \times A_1 \times A_1$	0 0 0 0
A <sub>3</sub>	000	2 <i>T</i>	<i>D</i> <sub>4</sub>	$\sim$
B <sub>3</sub>	<u>4</u>	20	F <sub>4</sub>	<u>4</u> o
H <sub>3</sub>	<u> </u>	21	H <sub>4</sub>	<u> </u>

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Polyhedral groups, Platonic solids and root systems

#### 2 A Clifford way of doing orthogonal transformations

#### Olifford algebra and quaternions

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# Quaternion groups via the geometric product

- The 8 quaternions of the form  $(\pm 1, 0, 0, 0)$  and permutations are the Lipschitz units, the quaternion group in 8 elements.
- The 8 Lipschitz units together with  $\frac{1}{2}(\pm 1, \pm 1, \pm 1, \pm 1)$  are the Hurwitz units, the binary tetrahedral group of order 24. Together with the 24 'dual' quaternions of the form  $\frac{1}{\sqrt{2}}(\pm 1, \pm 1, 0, 0)$ , they form the binary octahedral group of order 48.
- The 24 Hurwitz units together with the 96 unit quaternions of the form (0,±τ,±1,±σ) and even permutations, are called the lcosians. The icosian group is isomorphic to the binary icosahedral group with 120 elements.
- The unit spinors {1; e<sub>2</sub>e<sub>3</sub>; e<sub>3</sub>e<sub>1</sub>; e<sub>1</sub>e<sub>2</sub>} of Cl(3) are isomorphic to the quaternion algebra Ⅲ.

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# $H_4$ from icosahedral spinors

- The  $H_3$  root system has 30 roots e.g. simple roots  $\alpha_1 = e_2, \alpha_2 = -\frac{1}{2}((\tau 1)e_1 + e_2 + \tau e_3)$  and  $\alpha_3 = e_3$ .
- The subgroup of rotations is  $A_5$  of order 60
- These are doubly covered by 120 spinors of the form  $\alpha_1 \alpha_2 = -\frac{1}{2}(1-(\tau-1)e_1e_2+\tau e_2e_3), \ \alpha_1 \alpha_3 = e_2e_3$  and  $\alpha_2 \alpha_3 = -\frac{1}{2}(\tau-(\tau-1)e_3e_1+e_2e_3).$
- As a set of vectors in 4D, they are

 $(\pm 1, 0, 0, 0)$  (8 permutations) ,  $\frac{1}{2}(\pm 1, \pm 1, \pm 1, \pm 1)$  (16 permutations)

 $rac{1}{2}(0,\pm 1,\pm \sigma,\pm au)$  (96 even permutations) ,

which are precisely the 120 roots of the  $H_4$  root system.

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# Systematic construction of the polyhedral groups

- Multiplying together root vectors in the Clifford algebra gave a systematic way of constructing the binary polyhedral groups as 3D spinors = quaternions.
- The 6/12/18/30 roots in  $A_1 \times A_1 \times A_1/A_3/B_3/H_3$  generate 8/24/48/120 spinors.
- The discrete spinor group is isomorphic to the quaternion group Q / binary tetrahedral group 2T/ binary octahedral group 2O/ binary icosahedral group 2I).

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# Quaternionic representations of 3D and 4D Coxeter groups

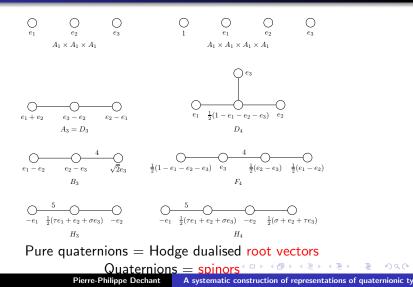
- Groups  $E_8$ ,  $D_4$ ,  $F_4$  and  $H_4$  have representations in terms of quaternions
- Extensively used in the high energy physics/quasicrystal/Coxeter/polytope literature and thought of as deeply significant, though not really clear why
- e.g.  $H_4$  consists of 120 elements of the form (±1,0,0,0),  $\frac{1}{2}(\pm 1,\pm 1,\pm 1,\pm 1)$  and (0,± $\tau$ ,±1,± $\sigma$ )
- Seen as remarkable that the subset of the 30 pure quaternions is a realisation of  $H_3$  (a sub-root system)
- Similarly,  $B_3$  and  $A_1 \times A_1 \times A_1$  have representations in terms of pure quaternions
- Clifford provides a much simpler geometric explanation

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Polyhedral groups, Platonic solids and root systems A Clifford way of doing orthogonal transformations Clifford algebra and quaternions

Representations from multivector groups: representations of qua Conclusions

### Quaternionic representations in the literature



# Demystifying Quaternionic Representations

- Pure quaternion subset of 4D groups only gives 3D group if the 3D group contains the inversion/pseudoscalar /
- e.g. does not work for the tetrahedral group  $A_3$ , but  $A_3 \rightarrow D_4$ induction still works, with the central node essentially 'spinorial'
- In fact, it goes the other way around: the 3D groups induce the 4D groups via spinors
- The rank-4 groups are also generated (under quaternion multiplication) by two quaternions we can identify as  $R_1 = \alpha_1 \alpha_2$  and  $R_2 = \alpha_2 \alpha_3$
- Can see these are 'spinor generators' and how they don't really contain any more information/roots than the rank-3 groups alone

# Quaternions vs Clifford versors

- Sandwiching is often seen as particularly nice feature of the quaternions giving rotations
- This is actually a general feature of Clifford algebras/versors in any dimension; the isomorphism to the quaternions is accidental to 3D
- However, the root system construction does not necessarily generalise
- 2D generalisation merely gives that  $I_2(n)$  is self-dual
- Octonionic generalisation just induces two copies of the above 4D root systems, e.g.  $A_3 \rightarrow D_4 \oplus D_4$
- Recently constructed  $E_8$  from the 240 pinors doubly covering 120 elements of  $H_3$  in  $2^3 = 8$ -dimensional 3D Clifford algebra

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# Polyhedral groups as multivector groups

Group	Discrete subgroup	Order	Action Mechanism
<i>SO</i> (3)	rotational (chiral)	G	$x \to \tilde{R}xR$
<i>O</i> (3)	reflection (full/Coxeter)	2  <i>G</i>	$x  ightarrow \pm  ilde{A} x A$
Spin(3)	binary	2  <i>G</i>	$(R_1,R_2) \rightarrow R_1R_2$
Pin(3)	pinory (?)	4  <i>G</i>	$(A_1,A_2) \to A_1A_2$

- e.g. the chiral icosahedral group has 60 elements, encoded in GA by 120 rotors, which form the binary icosahedral group
- together with the inversion/pseudoscalar *I* this gives 60 rotations and 60 rotoinversions, i.e. the full icosahedral group *H*<sub>3</sub> in 120 elements doubly covered by 240 pinors

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Some Group Theory: chiral, full, binary, pin

- Easy to calculate conjugacy classes etc of versors in GA
- Chiral (binary) polyhedral groups have irreps
- tetrahedral (12/24): 1, 1', 1",  $2_s$ ,  $2'_s$ ,  $2''_s$ , 3
- octahedral (24/48): 1, 1', 2, 2, 2, 2', 3, 3', 4,
- icosahedral (60/120): 1, 2<sub>s</sub>, 2'<sub>s</sub>, 3, 3, 4, 4<sub>s</sub>, 5, 6<sub>s</sub>
- All binary are discrete subgroups of SU(2) and all thus have a  $2_s$  spinor irrep
- Connection with Trinities and the McKay correspondence

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# Representations from Clifford multivector groups

- The usual picture of orthogonal transformations on an *n*-dimensional vector space is via *n* × *n* matrices acting on vectors, immediately making connections with representations = matrices satisfying the group multiplication laws.
- Easy to construct representations with (s)pinors in the 2<sup>n</sup>-dimensional Clifford algebra as reshuffling components.
- Spinors leave the original *n*-dimensional vector space invariant, reshuffle the components of the vector.
- But can also consider various representation matrices acting on different subspaces of the Clifford algebra.

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# Representations from Clifford multivector groups – trivial, parity, rotation representations

- The scalar subspace is one-dimensional.  $\tilde{R}1R = \tilde{R}R = 1$  gives the trivial representation, and likewise pinors A give the parity.
- The double-sided action  $\tilde{R} \times R$  of spinors R on a vector x in the *n*-dimensional vector space gives an  $n \times n$ -dimensional representation, which is just the usual rotation matrices.
- E.g.  $e_1e_2$  acting on  $x = x_1e_1 + x_2e_2 + x_3e_3$  gives  $e_2e_1xe_1e_2 = -x_1e_1 - x_2e_2 + x_3e_3$  which could also be expressed as  $\begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -x_1 \\ -x_2 \\ x_3 \end{pmatrix}$
- If the spinors were acting as  $R \times \tilde{R}$  would give a potentially different representation.

# Characters, their norm, and the Frobenius-Schur indicator

- Similarity transformed representations are also good representations, but are not fundamentally different: they are equivalent.
- So want a measure for a representation that is invariant under similarity transformations, e.g. the trace aka the character  $\chi$  of a matrix
- A class function i.e. the same within a conjugacy class because of the cyclicity of the trace
- The character norm  $||\chi||^2 := \frac{1}{|G|} \sum_{g \in G} |\chi(g)|^2$
- The Frobenius-Schur indicator  $v := \frac{1}{|G|} \sum_{g \in G} \chi(g^2)$

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# Real representations of real, complex, and quaternionic type

- $||\chi||^2 = \frac{1}{|G|} \sum_{g \in G} |\chi(g)|^2 = 1$ : representation of real type
- $||\chi||^2 = \frac{1}{|G|} \sum_{g \in G} |\chi(g)|^2 = 2$ : representation of complex type
- $||\chi||^2 = \frac{1}{|G|} \sum_{g \in G} |\chi(g)|^2 = 4$ : representation of quaternionic type
- Theorem: A complex representation is irreducible if and only if  $||\chi||^2 = 1$ .
- Theorem: A real representation is irreducible if and only if  $||\chi||^2 + \nu(\chi) = 2$ , e.g. 4 2 = 2 or 1 + 1 = 2.

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# Representations from Clifford multivector groups $-8 \times 8$ and $4 \times 4$ (whole algebra / even subalgebra)

- Rather than restricting oneself to the *n*-dimensional vector space, one can also define representations by  $2^n \times 2^n$ -matrices acting on the whole Clifford algebra, i.e. any element acting on an arbitrary element, e.g. here  $8 \times 8$ .
- Likewise, one can define  $2^{(n-1)} \times 2^{(n-1)}$ -dimensional spinor representations as acting on the even subalgebra.
- 3D spinors have components in (1, e<sub>1</sub>e<sub>2</sub>, e<sub>2</sub>e<sub>3</sub>, e<sub>3</sub>e<sub>1</sub>), multiplication with another spinor e.g. e<sub>1</sub>e<sub>2</sub> will reshuffle these components (e<sub>1</sub>e<sub>2</sub>, -1, -e<sub>3</sub>e<sub>1</sub>, e<sub>2</sub>e<sub>3</sub>)
- This reshuffling can therefore be described by a  $4 \times 4$ -matrix.

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# $4 \times 4$ – explicit example: $A_1^3$

(	1	0	0	0)	(	$^{-1}$	0	0	0	) (	0	0	0	$^{-1}$ )	$\begin{pmatrix} 0 \end{pmatrix}$	1	0	0)	
	0	1	0	0		0	$^{-1}$	0	0		0	0 -	-1	0	-1	0	0	0	
	0	0	1	0	'	0	0	$^{-1}$	0	,	0	1	0	0 0 0	0	0	0	1	,
	0	0	0	1)	l	0	0	0	-1	) (	1	0	0	0)	( <sub>0</sub>	0	-1	ر o	
(	ý 0	0	1	0	)	( 0	$^{-1}$	0	0	)	0	0	0	1)	( 0	0	$^{-1}$	0)	
	0	0	0	-1		1	0	0	0		0	0	1	1 0 0	0	0	0	1	
	-1	0	0	0	,	0	0	0	$^{-1}$	,	0	-1	0	0	1	0	0	0	
(	0	1	0	0	)	( 0	0	1	0	)	-1	0	0	。)	( 0	$^{-1}$	0	o )	

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#### Character table of Q

Q	1	-1	$\pm e_1 e_2$	$\pm e_2 e_3$	$\pm e_3 e_1$
1	1	1	1	1	1
1'	1	1	-1	-1	1
1″	1	1	-1	1	-1
1‴	1	1	1	-1	-1
4 <sub><i>H</i></sub>	4	-4	0	0	0

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#### $4 \times 4$ – explicit example: $A_3$

- As a set of vectors in 4D, they are  $(\pm 1, 0, 0, 0)$  (8 permutations),  $\frac{1}{2}(\pm 1, \pm 1, \pm 1, \pm 1)$  (16 permutations)
- Conjugacy classes:  $1 \cdot 4^2 + 1 \cdot (-4)^2 + 6 \cdot 0^2 + 8 \cdot 2^2 + 8 \cdot (-2)^2 = 32 + 32 + 32 = 96$
- $||\chi||^2 = 96/24 = 4$ , v = -2 and  $||\chi||^2 + v = 2$  i.e. real irreducible of quaternionic type.

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# $3 \times 3$ – explicit example: $H_3$

• Icosahedral spinors are

 $(\pm 1,0,0,0)$  (8 permutations) ,  $\frac{1}{2}(\pm 1,\pm 1,\pm 1,\pm 1)$  (16 permutations)  $\frac{1}{2}(0,\pm 1,\pm \sigma,\pm \tau)$  (96 even permutations) ,

• E.g. the rotation matrices corresponding to  $\alpha_1 \alpha_2$  and  $\alpha_2 \alpha_3$  via  $\tilde{R} \times R$  are

$$\frac{1}{2} \begin{pmatrix} \tau & \tau - 1 & -1 \\ 1 - \tau & -1 & -\tau \\ -1 & \tau & 1 - \tau \end{pmatrix} \text{ and } \frac{1}{2} \begin{pmatrix} \tau & 1 - \tau & -1 \\ 1 - \tau & 1 & -\tau \\ 1 & \tau & \tau - 1 \end{pmatrix}.$$

The characters  $\chi(g)$  are obviously 0 and  $\tau$ 

•  $||\chi||^2 = 120/120 = 1$ , v = 1 and  $||\chi||^2 + v = 2$  i.e. real irreducible of real type

#### $3 \times 3$ – explicit example: $H_3$ other way

• If the spinors were acting as  $R \times \tilde{R}$ , then

$$\frac{1}{2} \begin{pmatrix} \tau & 1-\tau & -1 \\ \tau-1 & -1 & \tau \\ -1 & -\tau & 1-\tau \end{pmatrix} \text{ and } \frac{1}{2} \begin{pmatrix} \tau & 1-\tau & 1 \\ 1-\tau & 1 & \tau \\ -1 & -\tau & \tau-1 \end{pmatrix},$$

with the same characters as before. Swapping the action of the spinor can change the representation.

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#### $4 \times 4$ – explicit example: $H_3$

Spinors α<sub>1</sub>α<sub>2</sub> and α<sub>2</sub>α<sub>3</sub> multiplying a generic spinor
 R = a<sub>0</sub> + a<sub>1</sub>e<sub>2</sub>e<sub>3</sub> + a<sub>2</sub>e<sub>3</sub>e<sub>1</sub> + a<sub>3</sub>e<sub>1</sub>e<sub>2</sub> from the left reshuffles the components (a<sub>1</sub>, a<sub>2</sub>, a<sub>3</sub>, a<sub>0</sub>) with the matrices given as

$$\frac{1}{2} \begin{pmatrix} -1 & \tau - 1 & 0 & -\tau \\ 1 - \tau & -1 & -\tau & 0 \\ 0 & \tau & -1 & \tau -1 \\ \tau & 0 & 1 - \tau & -1 \end{pmatrix}, \frac{1}{2} \begin{pmatrix} -\tau & 0 & 1 - \tau & -1 \\ 0 & -\tau & -1 & \tau -1 \\ \tau - 1 & 1 & -\tau & 0 \\ 1 & 1 - \tau & 0 & -\tau \end{pmatrix},$$

with characters -2 and  $-2\tau$ .

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#### $4 \times 4$ – explicit example $H_3$ : quaternionic type

- 120 4 × 4 matrices 9 conjugacy classes, with pairs that have  $\pm 2\chi_3$  so gives 4 times that of the 3 × 3 case
- $|G| \cdot ||\chi||^2 = 1 \cdot 4^2 + 1 \cdot (-4)^2 + 12 \cdot (-2\tau)^2 + 12 \cdot (2\tau)^2 + 12 \cdot (-2\sigma)^2 + 12 \cdot (2\sigma)^2 + 20 \cdot (-2)^2 + 20 \cdot (2)^2 + 30 \cdot 0^2 = 480$
- $||\chi||^2 = 480/120 = 4$ , v = -2 and  $||\chi||^2 + v = 2$  i.e. real irreducible of quaternionic type

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#### Character table of $I = A_5$

	1	1	20 <i>C</i> <sub>3</sub>	15 <i>C</i> <sub>2</sub>	12 <i>C</i> <sub>5</sub>	$12C_{5}^{2}$
ĺ	1	1	1	1	1	1
	3	3	0	-1	τ	σ
	3	3	0	-1	σ	τ
	4	4	1	0	-1	-1
	5	5	-1	1	0	0

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#### Character table of 21

1	1	20 <i>C</i> <sub>3</sub>	30 <i>C</i> <sub>2</sub>	12 <i>C</i> <sub>5</sub>	$12C_5^2$	-1	-20 <i>C</i> <sub>3</sub>	$-12C_{5}$	$-12C_{5}^{2}$
1	1	1	1	1	1	1	1	1	1
3	3	0	-1	τ	σ	3	0	τ	σ
3	3	0	-1	σ	τ	3	0	σ	$\tau$
4	4	1	0	-1	-1	4	1	-1	-1
5	5	-1	1	0	0	5	-1	0	0
2	2	-1	0	$-\sigma$	- au	-2	1	σ	τ
2	2	-1	0	- au	$-\sigma$	-2	1	τ	σ
4	4	1	0	-1	-1	-4	-1	1	1
6	6	0	0	1	1	-6	0	-1	-1
4 <sub><i>H</i></sub>	4	-2	0	$-2\tau$	$-2\sigma$	-4	2	2τ	2σ
$4_{\tilde{H}}$	4	-2	0	$-2\sigma$	$-2\tau$	-4	2	2σ	2τ

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# A general construction of representations of quaternionic type – canonical representations

- It had so far been overlooked that there is a systematic construction of representations of quaternionic type for 3D polyhedral groups
- This is simply due to the fact that the spinors in 3D provide a realisation of the quaternions
- Therefore spinors provide 4×4 representations of quaternionic type for all (though limited number of) possible groups
- However, they are canonical for a choice of 3D simple roots, i.e. there is a preferred amongst all similarity transformed versions
- These simple roots also determine the 3x3 rotation matrices and their reversed representations in a similar canonical way

#### Characters in general

• For a general spinor  $R = a_0 + a_1e_2e_3 + a_2e_3e_1 + a_3e_1e_2$  one has 3D character  $\chi = 3a_0^2 - a_1^2 - a_2^2 - a_3^2$  and representation

$$\frac{1}{2} \begin{pmatrix} a_0^2 + a_1^2 - a_2^2 - a_3^2 & -2a_0a_3 + 2a_1a_2 & 2a_0a_2 + 2a_1a_3 \\ 2a_0a_3 + 2a_1a_2 & a_0^2 - a_1^2 + a_2^2 - a_3^2 & -2a_0a_1 + 2a_2a_3 \\ -2a_0a_2 + 2a_1a_3 & 2a_0a_1 + 2a_2a_3 & a_0^2 - a_1^2 - a_2^2 + a_3^2 \end{pmatrix}$$

and the 4D rep and character are

$$\begin{pmatrix} a_0 & a_3 & -a_2 & a_1 \\ -a_3 & a_0 & a_1 & a_2 \\ a_2 & -a_1 & a_0 & a_3 \\ -a_1 & -a_2 & -a_3 & a_0 \end{pmatrix}, \begin{pmatrix} b_1 \\ b_2 \\ b_3 \\ b_0 \end{pmatrix} \text{ and } \chi = 4a_0.$$

• Characters of the representations are all determined by the spinor!

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Polyhedral groups, Platonic solids and root systems

- 2 A Clifford way of doing orthogonal transformations
- 3 Clifford algebra and quaternions

Representations from multivector groups: representations of quaternionic type





## Conclusions

- General construction of 4D root systems from 3D root systems – connections with McKay correspondence, Trinities, Moonshine etc
- Construction systematically and canonically gives representations of 4D root systems and 3D root systems in terms of (pure) quaternions
- Construction systematically and canonically gives construction of the polyhedral groups and their representations, in particular trivial, rotation and spinor representations of quaternionic type with relations among them and their characters

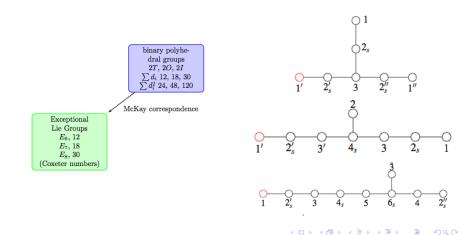
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# Arnold's Trinities

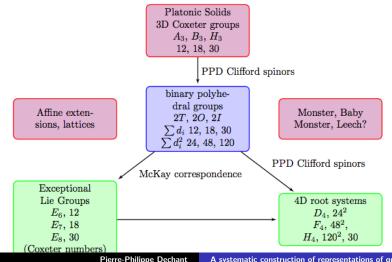
- Arnold noticed that often real, complex and quaternionic versions of a theory are remarkably similar
- Trinities  $(\mathbb{R}, \mathbb{C}, \mathbb{H})$
- $(\mathbb{R}P^{n}, \mathbb{C}P^{n}, \mathbb{H}P^{n})$ ,  $(\mathbb{R}P^{1} = S^{1}, \mathbb{C}P^{2} = S^{2}, \mathbb{H}P^{1} = S^{4})$ , the Möbius/Hopf bundles  $(S^{1} \to S^{1}, S^{4} \to S^{2}, S^{7} \to S^{4})$ ,  $(E_{6}, E_{7}, E_{8})$
- New connection between  $(A_3, B_3, H_3)$  and  $(D_4, F_4, H_4)$  (and  $(E_6, E_7, E_8)!$ ) via my Clifford spinor construction
- Also (24,48,120), binary polyhedral groups (2T,2O,2I) and (12,18,30) (see McKay correspondence)

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#### The McKay Correspondence



#### The McKay Correspondence



A systematic construction of representations of quaternionic ty

Some Group Theory: chiral, full, binary, pin

- Easy to calculate conjugacy classes etc of versors in GA
- Chiral (binary) polyhedral groups have irreps
- tetrahedral (12/24): 1, 1', 1",  $2_s$ ,  $2'_s$ ,  $2''_s$ , 3
- octahedral (24/48): 1, 1', 2,  $2_s$ ,  $2'_s$ , 3, 3',  $4_s$
- icosahedral (60/120): 1, 2<sub>s</sub>, 2'<sub>s</sub>, 3, 3, 4, 4<sub>s</sub>, 5, 6<sub>s</sub>
- All binary are discrete subgroups of SU(2) and all thus have a  $2_s$  spinor irrep
- Connection with Trinities and the McKay correspondence

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## The McKay Correspondence

More than E-type groups: the infinite family of 2D groups, the cyclic and dicyclic groups are in correspondence with  $A_n$  and  $D_n$ , e.g. the quaternion group Q and  $D_4^+$ . So McKay correspondence not just a trinity but ADE-classification. We also have  $l_2(n)$  on top of the trinity  $(A_3, B_3, H_3)$ 

rank-3 group diagram		binary	rank-4 group	diagram	Lie algebra	diagram	
$A_1 \times A_1 \times A_1$	000	Q	$A_1 \times A_1 \times A_1 \times A_1$	0 0 0 0	$D_4^+$		
						Ŷ	
A <sub>3</sub>	~~~~	27	$D_4$	<u> </u>	$E_6^+$	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	
B3	<u>₀</u> ₀	20	F4	<u> </u>	E <sub>7</sub> +	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	
H <sub>3</sub>	<u>⊶</u> 5	21	H <sub>4</sub>	o—o—o <u></u> 5	$E_8^+$	••••••••••	

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